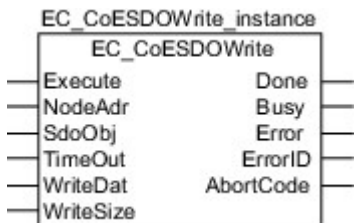


EC_CoESDOWrite

The EC_CoESDOWrite instruction writes a value to a CoE (CAN Application Protocol over EtherCAT) object of a specified slave on the EtherCAT network.

Instruction	Name	FB/ FUN	Graphic expression	ST expression
EC_CoESDOWrite	Write EtherCAT CoE SDO	FB		EC_CoESDOWrite_instance(Execute, NodeAdr, SdoObj, TimeOut, WriteDat, WriteSize, Done, Busy, Error, ErrorID, AbortCode);

Variables

	Meaning	I/O	Description	Valid range	Unit	Default
NodeAdr	Slave node address	Input	Node address of the slave to access	1 to 512 *1	---	---
SdoObj	SDO parameter		SDO parameter	---		
TimeOut	Timeout time		0: 2.0 s 1 to 65535: 0.1 to 6553.5 s	Depends on data type.	0.1 s	20 (2.0 s)
WriteDat	Write data		Write data		---	---
WriteSize	Write data size		Write data size *2	1 to 2048	Bytes	
AbortCode	Abort code	Output	Response code for SDO accesses specified by CoE	Depends on data type.	---	---

			0: Normal end		
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*1 The range is 1 to 256 for the NX502 CPU Unit.The range is 1 to 192 for the NX102 CPU Unit, NX1P2 CPU Unit, and NJ-series CPU Unit.

*2 The write data size may be less than 1 byte, e.g., if the write data is BOOL or a BOOL array. If it is less than 1 byte, set the value of WriteSize to 1.

	Boolean	Bit strings				Integers								Real numbers		Times, durations, dates, and text strings				
	BOOL	BYTE	WORD	DWORD	LONGWORD	USINT	UINT	UDINT	ULINT	SINT	INT	DINT	LINT	REAL	LREAL	TIME	DATE	TOD	DT	STRING
NodeAdr							OK													
SdoObj	Refer to EC_CoESDOWrite for details on the structure _sSDO_ACCESS.																			
TimeOut							OK													
WriteDat	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK	OK
	An enumeration, array, array element, structure member, or union member can also be specified.																			
WriteSize							OK													
AbortCode				OK																

Function

The EC_CoESDOWrite instruction writes data to the CoE object of the node specified with slave node address NodeAdr.

The content of WriteDat is written to the object. The size of data to write is specified with WriteSize.

The SDO parameter is specified with SdoObj.

The data type of SdoObj is structure _sSDO_ACCESS. The specifications are as follows:

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Name	Meaning	Description	Data type	Valid range	Unit	Default
SdoObj	SDO parameter	SDO parameter	_sSDO_ACCESS	---	---	---
Index	Index	Index number in the object dictionary defined in CoE	UINT	1 to 65535	---	---
Subindex	Subindex	Subindex number in the object dictionary defined in CoE	USINT	Depends on data type.		
IsCompleteAccess	Complete access	Specification of complete access of SDO TRUE: Access data for all subindexes FALSE: Access data for the specified subindex	BOOL			

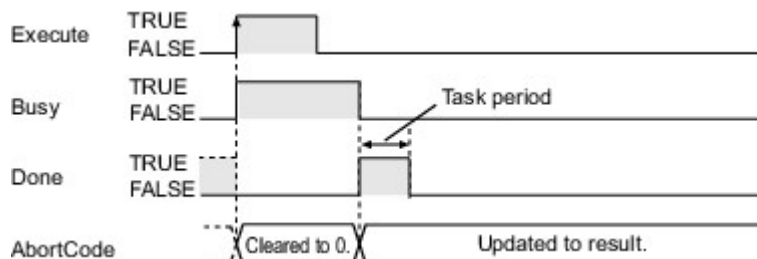
After the write is completed, the instruction waits for a response for the period of time specified with TimeOut.

The response is stored in AbortCode.

AbortCode is 0 for a normal response. A value is stored in AbortCode only when the value of ErrorID is 16#1804 (SDO abort response).

The value and meaning of AbortCode depend on the slave. Refer to the manual for the slave.

The following figure shows a timing chart. A value is stored in AbortCode when Busy changes to FALSE after the completion of instruction processing.



Related System-defined Variables

Name	Meaning	Data type	Description
<code>_EC_MBXSlaTbl[i]</code> "i" is the node address.	Message Communications Enabled Slave Table	BOOL	This variable indicates whether communications are possible for each slave. TRUE: Communications are possible. FALSE: Communications are not possible.

Additional Information

- Refer to the NJ/NX-series CPU Unit Built-in EtherCAT Port User's Manual (Cat. No. W505) or NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Built-in EtherCAT Port User's Manual (Cat.No. W562) for details on EtherCAT communications.
- Refer to [SDO Abort Codes](#) for the SDO abort codes.

Precautions for Correct Use

- Always use a variable for the input parameter to pass to WriteDat. A building error will occur if a constant is passed.
- Execution of this instruction is continued until completed even if the value of Execute changes to FALSE or the execution time exceeds the task period. The value of Done changes to TRUE when processing is completed. Use this to confirm normal completion of the execution.
- Refer to [Using this Section](#) for a timing chart for Execute, Done, Busy, and Error.
- This instruction can be used only for the NJ/NX-series and NY-series EtherCAT ports.
- You can execute a maximum of 32 of the following instructions at the same time: EC_CoESDOWrite, EC_CoESDORead, EC_StartMon, EC_StopMon, EC_SaveMon, EC_CopyMon, EC_DisconnectSlave, EC_ConnectSlave, EC_ChangeEnableSetting, EC_GetMasterStatistics, EC_ClearMasterStatistics, EC_GetSlaveStatistics, EC_ClearSlaveStatistics, IOL_ReadObj, and IOL_WriteObj.
- An error will occur in the following cases. Error will change to TRUE.

- a. The EtherCAT master is not in a state that allows message communications.
- b. The slave specified with NodeAdr does not exist.
- c. The slave specified with NodeAdr is not in a state that allows communications.
- d. The slave returns an error response.
- e. More than 32 of the following instructions were executed at the same time: EC_CoESDOWrite, EC_CoESDORead, EC_StartMon, EC_StopMon, EC_Save Mon, EC_CopyMon, EC_DisconnectSlave, EC_ConnectSlave, EC_ChangeEnableSetting, EC_GetMasterStatistics, EC_ClearMasterStatistics, EC_GetSlave Statistics, EC_ClearSlaveStatistics, IOL_ReadObj, and IOL_WriteObj.